

# Probability and Statistics

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## Continuous Random Variables

Let  $X$  be a continuous random variable. The probability distribution or probability density function (pdf) of  $X$  is a function  $f(x)$  such that for any two numbers  $a$  and  $b$  with  $a \leq b$ .

$$P(a \leq X \leq b) = \int_a^b f(x)dx$$

For a function  $f(x)$  to be a valid pdf, the following conditions must be satisfied:

1.  $f(x) \geq 0$  for any  $x \in (-\infty, \infty)$ .
2.  $\int_{-\infty}^{\infty} f(x)dx = 1$

A continuous random variable  $X$  is said to have a uniform distribution on the interval  $[A, B]$  if the pdf of  $X$  is:

$$f(x; A, B) = \begin{cases} \frac{1}{B-A} & , A \leq x \leq B \\ 0 & , \text{otherwise} \end{cases}$$

### Example

The direction of an imperfection with respect to a reference line on a circular object such as tires, brake rotors, etc. is in general subject to uncertainty. Consider the reference line connected the valve stem on a tire rim to the

center point. Let  $X$  be the angle measured clockwise to the location of the imperfection. One possible pdf for  $X$  is:

$$f(x) = \begin{cases} \frac{1}{360} & , 0 \leq x < 360 \\ 0 & , otherwise \end{cases}$$

Find the probability that there is an imperfection between the  $45^\circ$  and the  $90^\circ$  region on the rim.

$$\begin{aligned} P(45 \leq X \leq 90) &= \int_{45}^{90} \frac{1}{360} dy \\ &= \frac{1}{360} [y]_{y=45}^{y=90} \\ &= \frac{1}{360} (90 - 45) \\ &= \frac{45}{360} \\ &= \frac{1}{8} \end{aligned}$$

## Cumulative Distribution Function

The cumulative distribution function  $F(x)$  for a continuous random variable  $x$  is defined for every number by:

$$F(x) = P(X \leq x) = \int_{-\infty}^{\infty} f(s) ds$$

## Proposition

Let  $X$  be a continuous random variable with pdf  $f(x)$  and cdf  $F(x)$ . Then for any number  $a$ :

$$\begin{aligned} P(X > a) &= 1 - P(X \leq a) \\ &= 1 - \int_{-\infty}^a f(s) ds \\ &= 1 - F(a) \end{aligned}$$

For any numbers  $a$  and  $b$  with  $a \leq b$ :

$$\begin{aligned}P(a \leq X \leq b) &= \int_a^b f(s)ds \\&= \int_{-\infty}^a f(s)ds + \int_a^b f(s)ds - \int_{-\infty}^a f(s)ds \\&= \int_{-\infty}^b f(s)ds - \int_{-\infty}^a f(s)ds \\&= F(b) - F(a)\end{aligned}$$

### Example

Let  $p$  be a number between 0 and 1. The  $(100p)$ th percentile of the distribution of a continuous random variable  $X$ , denoted by  $\eta(p)$ , is defined by:

$$p = P(x \leq \eta(p)) = F(\eta(p)) = \int_{-\infty}^{\eta(p)} f(x)dx$$

Using the previous tire rim example, find  $\eta(0.9)$ , i.e. the 90th percentile.

$$\begin{aligned}p &= P(x \leq \eta(p)) \\0.9 &= P(X \leq \eta(0.9)) \\&= F(\eta(0.9)) \\&= \int_{-\infty}^{\eta(0.9)} f(x)dx \\&= \int_0^{\eta(0.9)} \frac{1}{360}dx \\&= \frac{1}{360}[x]_{x=0}^{x=\eta(0.9)} \\&= \frac{1}{360}[\eta(0.9) - 0] \\&= \frac{\eta(0.9)}{360} \\ \eta(0.9) &= (0.9)(360)\end{aligned}$$

The median of a continuous distribution, denoted by  $\tilde{\mu}$ , is the 50th percentile and also has special importance.

$$\tilde{\mu} = \eta(0.5)$$

$$0.5 = F(\eta(0.5)) = F(\tilde{\mu}) = \int_{-\infty}^{\tilde{\mu}} f(x)dx$$

## Expected Values and Variance

The expected values and variance of a continuous random variable are similar to those of a discrete random variable. Instead of  $\sum$ , we use  $\int$ .

Expected value of  $X$ :

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx$$

where  $f(x)$  is the pdf of  $X$ .

Expected value of  $Y = h(X)$ :

$$E(Y) = E(h(X)) = \int_{-\infty}^{\infty} h(x)f(x)dx$$

Variance of  $X$ :

$$V(X) = \int_{-\infty}^{\infty} (x - E(X))^2 f(x)dx$$

Standard Deviation of  $X$ :

$$\sigma_x = \sqrt{V(X)}$$

## Example

Using the previous tire rim example:

$$\begin{aligned} E(X) &= \int_{-\infty}^{\infty} f(x) dx \\ &= \int_0^{360} x \frac{1}{360} dx \\ &= \frac{1}{360} \frac{1}{2} [x^2]_{x=0}^{x=360} \\ &= \frac{1}{2} \frac{1}{360} [360^2 - 0^2] \\ &= \frac{1}{2} \frac{1}{360} 360^2 \\ &= \frac{1}{2} 360 = 180 \\ V(X) &= \int_{-\infty}^{\infty} (x - E(X))^2 f(x) dx \\ &= \int_{-\infty}^{\infty} (x - 180)^2 f(x) dx \\ &= \int_0^{360} (x - 180)^2 f(x) dx \\ &= \dots \end{aligned}$$

We can also use the proposition that  $V(X) = E(X^2) - [E(X)]^2$ :

$$\begin{aligned}
 E(X^2) &= \int_{-\infty}^{\infty} x^2 f(x) dx \\
 &= \int_0^{360} x^2 f(x) dx \\
 &= \int_0^{360} x^2 \frac{1}{360} dx \\
 &= \frac{1}{360} \int_0^{360} x^2 dx \\
 &= \frac{1}{360} \frac{1}{3} [x^3]_{x=0}^{360} \\
 &= \frac{1}{3} \frac{1}{360} [360^3 - 0^3] \\
 &= \frac{1}{3} 360^2 \\
 V(X) &= E(X^2) - [E(X)]^2 \\
 &= \frac{360^2}{3} - 180^2 \\
 &= \frac{1}{3} 2^2 180^2 - 180^2 \\
 &= 180^2 \left[ \frac{4}{3} - 1 \right] \\
 &= \frac{180^2}{3} \\
 \sigma_x &= \sqrt{V(X)} \\
 &= \frac{180}{\sqrt{3}} \\
 &\approx 104
 \end{aligned}$$

## Discrete vs Continuous Median

Given discrete quiz scores 6, 7, and 9, the median score is 7. For continuous values, the generation property of median  $\tilde{\mu}$  is:

$$\tilde{\mu} = \eta(0.5)$$

A continuous random variable  $X$  is said to have a normal distribution with parameters  $\mu$  and  $\sigma$  (or  $\mu$  and  $\sigma_2$ ), where:

$$-\infty < \mu < \infty$$

$$\mu \in (-\infty, \infty)$$

$$\mu \in \mathbb{R}$$

$\mu$  is a real number

and  $\sigma > 0$ , if the pdf of  $X$  is:

$$f(x; \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/(2\sigma)^2}$$

for any  $x \in \mathbb{R}$ .

If you have any questions, comments, or concerns, please contact me at [alvin@omgimanerd.tech](mailto:alvin@omgimanerd.tech)